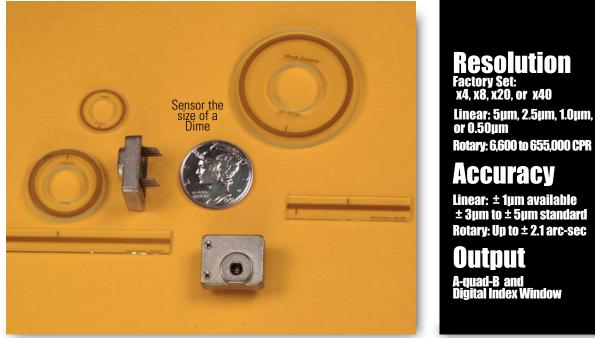




# **Mercury TM 1500P PCB-Mount Digital Encoders** Factory Set Resolution to 0.50µm

**Reflective Linear and Rotary Encoders** 



The Mercury 1500P encoder is a digital output system. Designed for PC board mounting, it is available with linear or rotary scales. Mercury's space-saving, integrated configuration gives OEM system designers a breakthrough in performance.

#### Imagine what you can do with this!

OEMs can now use encoders for closed loop control where it was previously not possible or cost effective. Engineers can achieve dramatic improvements in system speed, throughput, and reliability, while reducing cost, size and weight. The Mercury 1500P series kit encoders make it all possible. The digital output sensors mount directly on your printed circuit board within an EMI shielded module. The low Z height of the sensor, only 5.6mm, opens up exciting design possibilities.

### **Standard Features**

- Small PCB mount sensor
- Sensor is 5.6mm (H) x 12.7mm (W) x 15.2mm (L) and weighs 2.6g
- Resolution: Linear 5, 2.5, 1.0, 0.5µm; Rotary 6,600 to 655,000 CPR
- Digital Differential Outputs: A-guad-B and Index window
- Bi-directional Index window signal
- Index mark at the center or end of the glass scale (linear)

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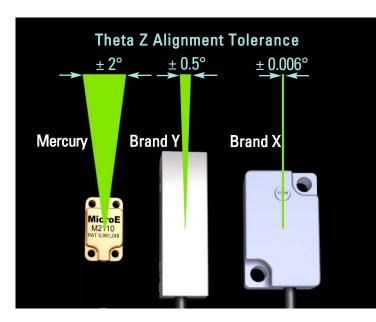
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#### Optional features

 Glass scale length or diameter: Linear lengths from 5mm to 2m Rotary diameters from 12mm to 108mm



# **Broader Alignment Tolerances**, **Increased Standoff Clearance**, Smallest Sensor and More Why Mercury Encoders Make It Easier To Design High Performance Into Your Enginment



### Alignment Tolerance Comparison\*\*

#### Eliminate the Frustration of Touchy Encoder Alignment

#### Mercury Solves this Problem for Good

Fussy alignment is no longer a concern. With Mercury's patented PurePrecision<sup>™</sup> optics, advanced SmartPrecision<sup>™</sup> electronics and LED alignment indicators, you can push the sensor against your reference surface, tighten the screws and you're finished. Try that with brand X or Y.

This performance is possible thanks to relaxed alignment tolerances, particularly in the theta Z axis. Mercury offers a  $\pm$  2° sweet spot— that's a 300% improvement over the best competitive encoder. And that will result in dramatic savings in manufacturing costs.

No other commercially available encoder is easier to align, easier to use, or easier to integrate into your designs.

	Mercury*	Brand X	Brand Y	Mercury vs. Best Competitor
Z Standoff	± 0.15mm	± 0.1mm	± 0.1mm	Mercury is 50% better
Y	± 0.20mm for linear ± 0.10mm for rotary ≥19mm dia.	± 0.1mm	unspecified	Mercury is 100% better
theta X	± 1.0°	unspecified	± 1.0°	
theta Y	± 2.0°	± 0.1°	± 1.0°	Mercury is 100% better
theta Z	± 2.0°	± 0.006°	± 0.5°	Mercury is 300% better

\*Measured at a constant temperature for one axis at a time with all other axes at their ideal positions.

\*\*Based on published specifications

### Mercury Can Reduce System Size and Cost

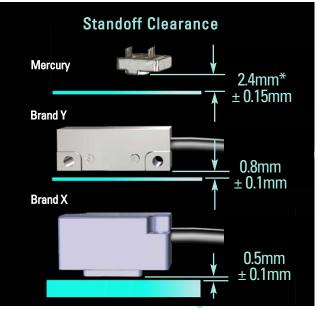
Mercury's sensor height is 44% shorter than competitive encoders, making it easy to fit into your design. This reduction can also cut total system weight and cost by allowing the use of smaller motors and stages. Safe system operation is also enhanced thanks to Mercury's generous standoff clearance– 200% greater than other encoders. And it's standoff tolerance is 50% greater than the best alternative. This significantly relaxes mechanical system tolerances, while reducing system costs.

### Mechanical Dimension Comparison\*\*

	Mercury	Brand X	Brand Y	Mercury vs. Best Competitor
Sensor Z height	8.4mm	23mm	15mm	44% better
Standoff clearance	2.4mm	0.5mm	0.8mm	200% better
Standoff tolerance	± 0.15mm	±0.1mm	± 0.1mm	50% better
System height	11.7mm	28.5mm	15.8mm	26% better

\*\*Based on published specifications

Note: Mercury 1500P is even smaller at 5.6mm sensor height



\* Dimensions shown illustrate encoder system standoff clearance; see Mercury Encoder Interface Drawings for correct design reference surfaces.

# **System Specifications** Resolution and Maximum Speed

Mercury 1500P systems have factory set interpolation: x4, x8, x20, x40. Below is the table of available resolutions.

### Linear - 20µm grating pitch

Interpolation	Resolution	Maximum Speed
x4	5.000µm/count	7200mm/s
x8	2.500µm/count	7200mm/s
x20	1.000µm/count	7200mm/s
x40	0.500µm/count	7200mm/s

## Rotary - 20µm grating pitch

Rotary	Fundamental	Interpolation
Glass Scale	Resolution	Below is a table of the available resolutions.
Diameter		

0.472" [12.00mm]	1650 CPR		x4	x8	x20	x40
		interpolated resolution (CPR)	6,600	13,200	33,000	66,000
		interpolated resolution (arc-sec/count)*	196.4	98.2	39.2	19.64
		interpolated resolution (µrad/count)*	952	476	190.3	95.2
		maximum speed (RPM)	13090	13090	13090	13090
0.750" [19.05mm]	2500 CPR		x4	x8	x20	x40
		interpolated resolution (CPR)	10,000	20,000	50,000	100,000
		interpolated resolution (arc-sec/count)*	129.6	64.8	25.9	12.96
		interpolated resolution (µrad/count)*	628	314	125.6	62.8
		maximum speed (RPM)	8640	8640	8640	8640
1.250" [31.75mm]	4096 CPR		x4	x8	x20	x40
		interpolated resolution (CPR)	16,384	32,768	81,920	163,840
		interpolated resolution (arc-sec/count)*	79.1	39.6	15.82	7.91
		interpolated resolution (µrad/count)*	383	191.7	76.6	38.3
		maximum speed (RPM)	5273	5273	5273	5273
2.250" [57.15mm]	8192 CPR		x4	x8	x20	x40
		interpolated resolution (CPR)	32,768	65,536	163,840	327,680
		interpolated resolution (arc-sec/count)*	39.6	19.78	7.92	3.96
		interpolated resolution (µrad/count)*	191.7	95.8	38.3	19.17
		maximum speed (RPM)	2637	2637	2637	2637
4.250" [107.95mm]	16384 CPR		x4	x8	x20	x40
		interpolated resolution (CPR)	65,536	131,072	327,680	655,360
		interpolated resolution (arc-sec/count)*	19.78	9.89	3.96	1.978
		interpolated resolution (µrad/count)*	95.8	47.9	19.16	9.58
		maximum speed (RPM)	1318	1318	1318	1318

\* Resolution values shown are approximate. To calculate exact resolution values, convert from CPR (Counts Per Revolution) to the desired units.

Note: Specifications assume XOR function which is available in all standard controllers.

All Specifications are subject to change. All data is accurate to the best of our knowledge. MicroE Systems is not responsible for errors.

# **System Specifications**

### System

Grating Period	20µm						
System Resolution	1 Бµт, 2.5µт, 1.00µт, or 0.50µт (linear)						
Linear Accuracy*	Better than ±1µ	Better than ±1µm** available; contact MicroE					
	Better than ±3µ	m** up to 130mm, ±5µn	n from 155mm to 1m,				
	±5µm per mete	r from 1m to 2m					
*Maximum peak to peak en used at room temperature a	rror over the specified m and with MicroE interpol	ovement when compared to a NIST ation electronics.	F-traceable laser interferometer standard,				
**Or +/- one quadrature co	unt, whichever error valu	ue is greater.					
Rotary Accuracy*	Scale O.D.	Microradians**	Arc-Seconds**				
	12.00mm	±100	±21				
	19.05mm	±63	±13				
31.75mm ±38 ±7.8							

±19

±10

±3.9

±2.1

\*Based on ideal scale mounting concentricity

\*\*Or +/- one quadrature count, whichever error value is greater

57.15mm

107.95mm

#### **Sensor Size**

W:	12.70mm	0.500"	
L:	15.24mm	0.600"	
H:	5.59mm	0.220"	

## **Operating and Electrical Specifications**

Power Supply	5VDC ±5% @ 33mA <sup>1</sup>
Temperature	
Operating:	0 to 70°C
Storage:	-20 to 70°C
Humidity:	10 - 90% RH non-condensing
Shock:	1500G 0.5 ms half sine (Sensor)
Sensor Weight:	2.6g

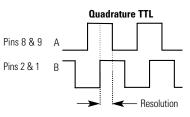
<sup>1</sup> Note: a voltage regulator on the customer's printed circuit board, such as Analog Devices' ADP 3334 or equivalent, is recommended at the 5V input to the encoder for maximum reliability.

### **Mercury 1500P Outputs**

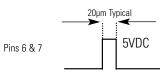
10-pin interface					
PIN	FUNCTION				
1	В -				
2	В +				
3	Sin + *				
4	Cos + *				
5	+ 5 V DC				
6	Index Window +				
7	Index Window -				
8	A +				
9	A -				
10	Ground				

\* Analog outputs are for sensor alignment only.

**Output Signals\*\*** 

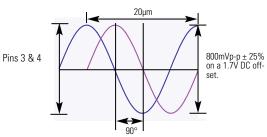


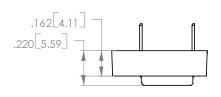
#### Index Window



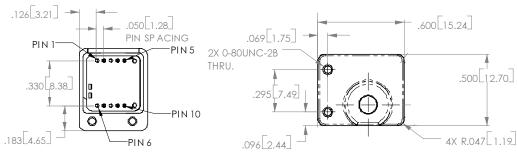
\*\* Inverse signals not shown for clarity.

#### **Alignment Signals**





### **Mechanical Information - Sensor**



# Scale Specifications Standard and Customized Scales

MicroE Systems offers a wide array of chrome on glass scales for the highest accuracy and best thermal stability. Easy to install, standard linear and rotary scales meet most application requirements. Customized linear, rotary, and rotary segment scales are available where needed. All scales include an optical index. Mercury's glass scales save time by eliminating motion system calibrations or linearity corrections required by other encoders, and provide better thermal stability than metal tape scales.

#### **Options include:**

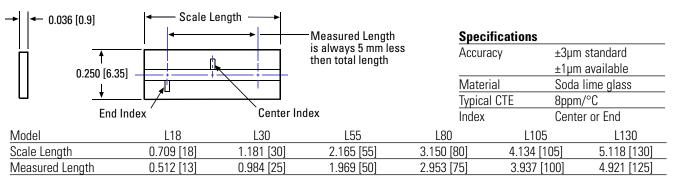
- Standard linear: 18mm 2m
- Standard rotary: 12mm 107.95mm diameter, with or without hubs
- Custom linear\*: special lengths, widths, thickness, index mark locations and special low CTE materials
- Custom rotary\*: special ID's, OD's (up to 304.8mm), index mark outside the main track and special low CTE materials
- Mounting of hubs for rotary scales: MicroE Systems can mount and align standard, custom, or customer-supplied hubs
- Rotary segments\*: any angle range; wide range of radius values

\*Custom scales or rotary segments are available in OEM quantities. Contact your local MicroE Systems sales office.

# **Standard Short Linear Scales**

### 130mm and Shorter

Key: inches[mm]

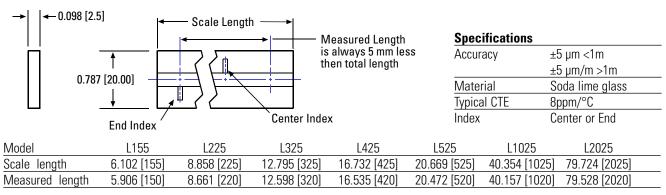


Custom scales available

# **Standard Long Linear Scales**

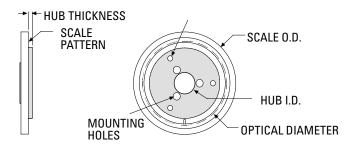
#### 155mm and Longer

Key: inches[mm]



Custom scales available

# **Standard Rotary Scales**



<b>Specifications</b>	
Material	Soda lime glass
Typical CTE	8ppm/°C

Key: inches[mm]

Model No.	Scale Outer Diameter	Scale Inner Diameter	Optical Diameter	Hub Inner Diameter +.0005/-0.0000	Hub Thickness	Fundamental CPR
R1206	0.472 [12.00]	0.250 [6.35]	0.413 [10.50]	0.1253 [3.18]	0.040 [1.02]	1650
R1910	0.750 [19.05]	0.375 [9.52]	0.627 [15.92]	0.1253 [3.183]	0.040 [1.02]	2500
R3213	1.250 [31.75]	0.500 [12.70]	1.027 [26.08]	0.2503 [6.358]	0.050 [1.27]	4096
R5725	2.250 [57.15]	1.000 [25.40]	2.053 [52.15]	0.5003 [12.708]	0.060 [1.52]	8192
R10851	4.250 [107.95]	2.000 [50.80]	4.106 [104.30]	1.0003 [25.408]	0.080 [2.03]	16384

Custom scales available

# **How to Order Mercury 1500P Encoder Systems**

To specify your Mercury encoder with the desired scale, consult the chart below to create the correct part number for your order. Call MicroE Systems' Rapid Customer Response team for more information at [781] 266-5700.

#### Example (linear): M1540P-L55-C1 (rotary): M1540P-R3213-HB

	<u>M15xxP</u>	_	<u>Scale Model</u> –	Scale Mounting
M1504P = M1508P = M1520P = M1540P =	8x 20x	ition	Lxxx or Rxxxx	For Linear Scales: T = Tape Mounting C1 = 3 scale clamps* C2 = 10 scale clamps**
				Hubs for Rotary Scales: NH = No hub HE = for R1206 HA = for R1910 HB = for R3213 HC = for R5725 HD = for R10851

\* 3 clamps come standard with linear scales up to 130mm

\*\* 10 clamps come standard with linear scales 155mm or longer

All Specifications are subject to change. All data is accurate to the best of our knowledge.

MicroE Systems is not responsible for errors.



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